# Exponentially Convergent Multiscale Methods Based on Edge Coupling: Example of Helmholtz Equation

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- 2 Coarse-Fine Scale Decomposition
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## $\mathsf{Section}\ 1$

## Helmholtz Equation

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## Setting of Helmholtz Equation

Helmholtz equation with mixed boundary conditions:

$$\begin{cases} -\nabla \cdot (A\nabla u) - k^2 V^2 u = f, \text{ in } \Omega, \\ u = 0, \text{ on } \Gamma_D, \\ A\nabla u \cdot \nu = T_k u, \text{ on } \Gamma_N \cup \Gamma_R, \end{cases}$$
(1)

where  $A_{\min} \leq A(x) \leq A_{\max}$ ,  $\beta_{\min} \leq \beta(x) \leq \beta_{\max}$ ,  $V_{\min} \leq V(x) \leq V_{\max}$ ,  $T_k u = 0$  for  $x \in \Gamma_N$ , and  $T_k u = ik\beta u$  for  $x \in \Gamma_R$ .

Bilinear form:

$$a(u,v) := (A\nabla u, \nabla v)_{\Omega} - k^2 (V^2 u, v)_{\Omega} - (T_k u, v)_{\Gamma_N \cup \Gamma_R}.$$
 (2)

Associated norm:

$$||u||_{\mathcal{H}(\Omega)} := \int_{\Omega} A|\nabla u|^2 + k^2 |Vu|^2.$$
 (3)

# Applications of Helmholtz Equation

- 1 Wave mechanics
- 2 Electrostatics
- 3 Seismology
- 4 Acoustics



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# Pollution Effect

- I. Babuska, SINUM 1997.
  - Mesh size sufficient to address the wave length: O(1/k).
  - For standard FEM:  $h = O(1/k^2)$ .
  - Ideal method: H = O(1/k)!
    - *hp*−FEM with local polynomial of order *O*(log *k*). Melenk, Math. Comp., 2011.
    - Localizable orthogonal decompositions (LOD) with basis of support size  $O(H \log(1/H))$ . Peterseim, Math. Comp., 2014.
    - Multiscale edge basis with exponential rate of convergence.
    - A later work: Partition of unity method (PUM) with exponential rate of convergence. Ma, 2021.
  - Fast solver with preconditioner: Ying, CPAM, 2011.

# Sketch of Contributions

*Our result*: on a mesh of lengthscale H = O(1/k), u can be computed by

$$u = \underbrace{\sum_{i \in I_1} c_i \psi_i^{(1)}}_{(\mathsf{I})} + \underbrace{\sum_{i \in I_2} \psi_i^{(2)}}_{(\mathsf{II})} + C \exp(-bm^{\frac{1}{d+1}})$$
 (Energy norm)

b, C constants independent of H, k.  $\psi_i^{(1)}, \psi_i^{(2)}$  local support of size H. •  $\psi_i^{(1)}$  obtained by *local* SVD of  $\mathcal{L}_{\theta}$  $#I_1 = O(m/H^d)$ •  $\psi_i^{(2)}$  obtained by solving *local*  $\mathcal{L}_{\theta} u = f$  $\#I_2 = O(1/H^d)$ •  $c_i$  obtained by Galerkin's methods with basis functions  $\psi_i^{(1)}$  $\blacksquare (II) = O(H) \text{ (Energy norm)}$ 

A data-adaptive coarse-fine scale decomposition

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# Continuity Estimate and Stability

#### Continuity estimate:

$$|a(u,v)| \le C_c ||u||_{\mathcal{H}(\Omega)} ||v||_{\mathcal{H}(\Omega)}.$$
(4)

• Stability: Let  $N_k f := u$  be the solution operator.

$$\sup_{f \in L^2(\Omega) \setminus \{0\}} \frac{\|N_k f\|_{\mathcal{H}}}{\|f\|_{L^2(\Omega)}} =: C_{\text{stab}} < \infty.$$
(5)

Assumption on the stability constant:  $C_{\text{stab}} \leq C_0 k^{\alpha}$ .

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## Section 2

#### Coarse-Fine Scale Decomposition

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## Detour on Elliptic PDEs

Problem formulation:

$$\begin{cases} -\nabla \cdot (a\nabla u) = f, & \text{in } \Omega, \\ u = 0, & \text{on } \partial \Omega. \end{cases}$$

- $\Omega = [0,1]^2 \text{ and } u \in H^1_0(\Omega), f \in L^2(\Omega).$
- **Galerkin methods**: choose a finite-dim space  $V_H \subset H_0^1(\Omega)$ :

Find  $u_H \in V_H$  such that  $\int_{\Omega} a \nabla u_H \cdot \nabla v = \int_{\Omega} f v$  for any  $v \in V_H$ . *Optimality*: (notation  $||u||_{H^1_a(\Omega)} := \int_{\Omega} a |\nabla u|^2$ )  $||u - u_H||_{H^1_a(\Omega)} = \inf_{v \in V_H} ||u - v||_{H^1_a(\Omega)}$ .

 $V_H$  needs to approximate the solution space well in the  $H^1_a(\Omega)$  norm.

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# Explore the Solution Space

- Mesh structure: nodes, edges and elements.
- Split the solution locally: in each T,  $u = u_T^{h} + u_T^{b}$ .  $\begin{cases}
  -\nabla \cdot (A \nabla u_T^{h}) - k^2 V^2 u_T^{h} = 0 \text{ in } T \\
  u_T^{h} = u \text{ on } \partial T, \\
  U_T^{h} = u \text{ on } \partial T, \\
  U_T^{h} = 0 \text{ on } \partial T.
  \end{cases}$   $\begin{cases}
  -\nabla \cdot (A \nabla u_T^{b}) - k^2 V^2 u_T^{b} = f \text{ in } T \\
  u_T^{b} = 0 \text{ on } \partial T.
  \end{cases}$   $x \in \mathcal{N}_H, e \in \mathcal{E}_H, T \in \mathcal{T}_H$
- Merge: For each T,  $u^{\mathsf{h}}(x) = u_T^{\mathsf{h}}(x)$ and  $u^{\mathsf{b}}(x) = u_T^{\mathsf{b}}(x)$ , when  $x \in T$ .

#### Coarse-fine Scale Decomposition

- Poincaré inequality:  $||v||_{L^2(T)} \leq C_P H ||\nabla v||_{L^2(T)}$ .
- Mesh assumption:  $H \leq A_{\min}^{1/2}/(\sqrt{2}C_P V_{\max}k)$ .
- Decomposition:  $u = u^{\mathsf{h}} + u^{\mathsf{b}} \in V^{\mathsf{h}} + V^{\mathsf{b}}$ .

$$V^{\mathsf{h}} := \{ v \in \mathcal{H}(\Omega) : -\nabla \cdot (A\nabla v) - k^2 V^2 v = 0 \text{ in each } T \in \mathcal{T}_H, \\ A\nabla v \cdot \nu = T_k v, \text{ on } \Gamma_N \cup \Gamma_R \} \quad (harmonic part) \\ V^{\mathsf{b}} := \{ v \in \mathcal{H}(\Omega) : v = 0 \text{ on each } e \in \mathcal{E}_H \} \quad (bubble part) \end{cases}$$

For  $v \in V^{\mathsf{h}}$  and  $w \in V^{\mathsf{b}}$ , it holds that a(v, w) = 0.

This decomposition makes sense by the  $C^{\alpha}$  estimate of the solution.

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## Small Bubble Part

Bubble part is local and small:

$$\|u^{\mathsf{b}}\|_{\mathcal{H}(\Omega)} \leq \frac{3C_P}{A_{\min}^{1/2}} H \|f\|_{L^2(\Omega)}.$$

i.e.  $u^{b}$  oscillates at a frequency larger than O(1/H).

Bubble part is the fine scale part.

## Approximation of Harmonic Part

**Observation**:  $V^{h}$  is isomorphic to an edge space:

$$V^{\mathsf{h}} := \{ v \in \mathcal{H}(\Omega) : -\nabla \cdot (A\nabla v) - k^2 V^2 v = 0 \text{ in each } T \in \mathcal{T}_H, \\ A\nabla v \cdot \nu = T_k v, \text{ on } \Gamma_N \cup \Gamma_R \}$$

Functions in  $V^{h}$ , locally solving Helmholtz-harmonic problems, only depend on values of v on edges.

Galerkin's solution  $u_H$  now only approximates the harmonic part.

#### Section 3

## Exponentially Efficient Edge Basis

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## Localization to Edge Functions

• Edge function:  $u^{\mathsf{h}} : \Omega \to \mathbb{R}$  restricted to edges:  $\tilde{u}^{\mathsf{h}} : E_H \to \mathbb{R}$ .

Task: find edge basis functions to approximate  $\tilde{u}^{h}$ .

• Localization to each edge:  $(\tilde{u}^{h} - I_{H}\tilde{u}^{h})|_{e}$  vanishes at nodal points where  $I_{H}$  is nodal interpolation operator, e.g., by linear tent functions.

Next: find edge basis functions to approximate  $(\tilde{u}^{h} - I_{H}\tilde{u}^{h})|_{e}$  for each e.

The edge residual  $R_e \tilde{u}^{\mathsf{h}} := (\tilde{u}^{\mathsf{h}} - I_H \tilde{u}^{\mathsf{h}})|_e$  lies in the Lions-Magenes space, i.e. functions  $v \in H^{1/2}(e)$  s.t.  $\frac{v(x)}{\operatorname{dist}(x,\partial e)} \in L^2(e)$ , by the  $C^{\alpha}$  estimate.

### Local Approximation via Oversampling

• Oversampling: 
$$e \subset \omega_e := \overline{\bigcup \{T \in \mathcal{T}_H : \overline{T} \cap e \neq \emptyset\}}$$
.  
on  $e : u^{\mathsf{h}} - I_H u^{\mathsf{h}} = (u^{\mathsf{h}}_{\omega_e} - I_H u^{\mathsf{h}}_{\omega_e}) + (u^{\mathsf{b}}_{\omega_e} - I_H u^{\mathsf{b}}_{\omega_e})$ .  
 $u^{\mathsf{h}}_{\omega_e}, u^{\mathsf{b}}_{\omega_e}$ : oversampling harmonic / bubble part.

• Special harmonic function:  $u^{s} \in V^{h}$  is a special harmonic function such that its restriction on each edge  $e \in E_{H}$  equals  $\tilde{u}_{\omega_{e}}^{b} - I_{H}\tilde{u}_{\omega_{e}}^{b}$ . Recall the definition:

$$\begin{cases} -\nabla \cdot (A\nabla u_{\omega_e}^{\mathsf{h}}) - k^2 V^2 u_{\omega_e}^{\mathsf{h}} = 0 \text{ in } \omega_e \\ u_{\omega_e}^{\mathsf{h}} = u \text{ on } \partial \omega_e, \\ -\nabla \cdot (A\nabla u_{\omega_e}^{\mathsf{h}}) - k^2 V^2 u_{\omega_e}^{\mathsf{h}} = f \text{ in } \omega_e \\ u_{\omega_e}^{\mathsf{h}} = 0 \text{ on } \partial \omega_e. \end{cases}$$

Next: Restrictions of harmonic part are of low complexity!

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## Local Norm for Approximation

• The  $\mathcal{H}^{1/2}(e)$  norm: (connect back to energy norms)

$$\|\tilde{\psi}\|_{\mathcal{H}^{1/2}(e)}^2 := \int_{\Omega} A|\nabla\psi|^2 + k^2 |V\psi|^2.$$

where  $\psi$  is the harmonic extension of  $\tilde{\psi}$  to neighboring elements.

#### Theorem (Edge Coupling)

If on each edge, there is  $\tilde{v}_e$  such that the local error satisfies

$$\|\tilde{u}_{\omega_e}^{\mathsf{h}} - I_H \tilde{u}_{\omega_e}^{\mathsf{h}} - \tilde{v}_e\|_{\mathcal{H}^{1/2}(e)} \le \epsilon_e,$$

then the global error satisfies

$$\|u^{\mathsf{h}} - u^{\mathsf{s}} - I_H u^{\mathsf{h}} - \sum_{e \in \mathcal{E}_H} v_e\|_{\mathcal{H}(\Omega)}^2 \le C_{\text{mesh}} \sum_{e \in \mathcal{E}_H} \epsilon_e^2.$$

# Low Complexity: Restrictions of Harmonic Part

#### Theorem (Y. Chen, T.Y. Hou, Y. Wang, 2021, 2022)

There exist constants C, b, such that for all m, we can find an (m-1)dimensional space  $W_e^m = \text{span } \{ \tilde{v}_e^k \}_{k=1}^{m-1}$  so that for any harmonic function v in  $\omega_e$ .

$$\min_{\tilde{v}_e \in W_e^m} \|v - I_H v - \tilde{v}_e\|_{\mathcal{H}^{1/2}(e)} \le C \exp\left(-bm^{\frac{1}{d+1}}\right) \|v\|_{\mathcal{H}(\omega_e)}.$$

•  $W_e^m$  obtained by left singular vectors of the operator  $R_e v = v - I_H v$ .

• Proof technique combines [Babuska, Lipton 2011] and  $C^{\alpha}$  estimates.

Essentially Helmholtz operator resembles an elliptic operator locally.

 $\bullet \ u = u^{\mathsf{h}} + \underbrace{u^{\mathsf{b}}}_{u^{\mathsf{b}}}$ 

(harmonic-bubble splitting)

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part of (II), small  

$$u = u^{h} + u^{b}$$
(harmonic-bubble splitting)  

$$u^{h} = (u^{h} - I_{H}u^{h}) + I_{H}u^{h}$$
(interpolation part)  

$$(u^{h} - I_{H}u^{h})|_{e} = (u^{h}_{\omega_{e}} - I_{H}u^{h}_{\omega_{e}})|_{e} + u^{s}|_{e}$$

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part of (II), small  

$$u = u^{h} + u^{b} \qquad (harmonic-bubble splitting)$$

$$u^{h} = (u^{h} - I_{H}u^{h}) + I_{H}u^{h} \qquad (interpolation part)$$

$$u^{h} = (u^{h} - I_{H}u^{h})|_{e} = (u^{h}_{\omega_{e}} - I_{H}u^{h}_{\omega_{e}})|_{e} + u^{s}|_{e}$$

$$u^{h}|_{e} = \sum_{j=1}^{restriction of harmonic part} part of (II), small$$

$$(u^{h} - I_{H}u^{h})|_{e} = \sum_{j=1}^{restriction sin (I)} + C \exp\left(-bm\frac{1}{d+1}\right) ||u^{h}_{\omega_{e}}||_{\mathcal{H}(\omega_{e})}$$

$$(u^{h}_{\omega_{e}} - I_{H}u^{h}_{\omega_{e}})|_{e} = \sum_{j=1}^{m-1} c_{j}v^{j}_{e} + C \exp\left(-bm\frac{1}{d+1}\right) ||u^{h}_{\omega_{e}}||_{\mathcal{H}(\omega_{e})}$$

$$(basis functions not dependent on f, but on \mathcal{L}_{\theta} \qquad (local, and small)$$

$$(basis functions not dependent on f, but on \mathcal{L}_{\theta} \qquad (local, and small)$$

## Section 4

Multiscale Method

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# Overall Exponential Accuracy in Approximation

By the local to global error estimate, we have the overall approximation accuracy using  $V_{H,m}$  consisting of basis functions in (I):

#### Theorem (Global Approximation)

$$\min_{v \in V_{H,m}} \|u^{\mathsf{h}} - u^{\mathsf{s}} - v\|_{\mathcal{H}(\Omega)} \le C(C_{\mathrm{stab}}(k) + H) \exp\left(-bm^{\frac{1}{d+1}}\right) \|f\|_{L^{2}(\Omega)},$$

where C is a generic constant independent of k, m, H.

## Multiscale Framework for Galerkin Methods

- Handle coarse part  $u^{h} u^{s}$  and fine part  $u^{b} + u^{s}$  separately. Choose a finite-dim trial space  $S \subset V^{h}$ , compute locally  $u^{b} + u^{s}$ , and then:
- find  $u_S \in S$  such that  $a(u_S, v) = (f, v)_{\Omega} a(u^{\mathsf{b}} + u^{\mathsf{s}}, v)$  for any  $v \in S_{\text{test}}$ .

• 
$$S_{\text{test}} = S$$
: Ritz-Galerkin;  
•  $S_{\text{test}} = \overline{S}$ : Petrov-Galerkin.

#### Approximation Implies Accuracy

#### Approximation Ability:

$$\eta^{\mathsf{h}}(S) := \sup_{f \in L^{2}(\Omega) \setminus \{0\}} \inf_{v \in S} \frac{\|u - v\|_{\mathcal{H}(\Omega)}}{\|f\|_{L^{2}(\Omega)}} \quad \text{with} \quad u = N_{k}f.$$
 (6)

Given that  $k\eta^{h}(S) \leq 1/(2C_{c}V_{\max})$ , for the Ritz-Galerkin method with  $\overline{S} = S$ , we have Quasi-optimal Approximation:

$$\|u^{\mathsf{h}} - u^{\mathsf{s}} - u_S\|_{\mathcal{H}(\Omega)} \le 2C_c \inf_{v \in S} \|u^{\mathsf{h}} - u^{\mathsf{s}} - v\|_{\mathcal{H}(\Omega)}.$$

#### Gårding-type inequality for a posteriori estimate.

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# Ritz-Galerkin Method

#### Theorem (Galerkin Exponential Accuracy)

Suppose  $Ck[(C_{stab}(k) + H) \exp\left(-bm^{\frac{1}{d+1}}\right) + H] \leq 1/(2C_cV_{max})$ , then using  $S = V_{H,m} + \overline{V_{H,m}}$  in Ritz-Galerkin method leads to a solution  $u_S$  such that

$$||u^{\mathsf{h}} - u^{\mathsf{s}} - u_{S}||_{\mathcal{H}(\Omega)} \le 2C_{c}C(C_{\mathrm{stab}}(k) + H)\exp\left(-bm^{\frac{1}{d+1}}\right)||f||_{L^{2}(\Omega)}.$$

- $m \sim \log^{d+2}(k)$  suffices for an exponential rate of convergence.
- $V_{H,m}$  and  $\overline{V_{H,m}}$  only differ on the edges connected to the boundary, where Robin boundary conditions make the operator non-Hermitian.

## Section 5

# Numerical Experiments

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## High Wavenumber Example

•  $A = V = \beta = 1$ ,  $k = 2^7$ , fine mesh  $h = 2^{-10}$ , coarse mesh  $H = 2^{-5}$ .

• Exact solution:  $u(x_1, x_2) = \exp(-ik(0.6x_1 + 0.8x_2))$ .



Figure: High wavenumber example. Left:  $e_{\mathcal{H}}$  versus m; right:  $e_{L^2}$  versus m.

#### High Contrast Example: Mie resonances

$$\Omega_{\varepsilon} = (0.25, 0.75)^2 \cap \bigcup_{j \in \mathbb{Z}^2} \varepsilon \left( j + (0.25, 0.75)^2 \right), \quad A(x) = \begin{cases} 1, & x \notin \Omega_{\varepsilon} \\ \varepsilon^2, & x \in \Omega_{\varepsilon} \end{cases}.$$

$$\beta = 1, V = 1, k = 9.$$



Figure: High contrast example. Left:  $e_{\mathcal{H}}$  versus m; right:  $e_{L^2}$  versus m.

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## Mixed Boundary and Rough Field Example

#### Rough media with mixed boundary conditions. (Artificial)



Figure: Left: the contour of A; right: relative errors in the energy norm.

# Section 6

Conclusions

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## Summary of the Framework

- **1** Galerkin solution as a quasi-optimal approximation.
- **2** Harmonic-bubble decomposition to avoid non positive definiteness in the whole domain.
- **3** Local nodal/edge basis construction for global error estimate.
- 4 Exponential decay of the error by oversampling method to achieve optimal design.
- **5** Extensive numerical experiments to corroborate the exponential rate of convergence.

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# Sketch of Contributions

*Our result*: on a mesh of lengthscale H = O(1/k), u can be computed by

$$u = \underbrace{\sum_{i \in I_1} c_i \psi_i^{(1)}}_{(I)} + \underbrace{\sum_{i \in I_2} \psi_i^{(2)}}_{(II)} + C \exp(-bm^{\frac{1}{d+1}})$$
 (Energy norm)

b,C constants independent of  $H,k.~\psi_i^{(1)},\psi_i^{(2)}$  local support of size H.

• 
$$\psi_i^{(1)}$$
 obtained by *local* SVD of  $\mathcal{L}_{\theta}$   
•  $\psi_i^{(2)}$  obtained by solving *local*  $\mathcal{L}_{\theta}u = f$   
 $\#I_1 = O(m/H^d)$   
 $\#I_2 = O(1/H^d)$ 

- $c_i$  obtained by Galerkin's methods with basis functions  $\psi_i^{(1)}$
- (II) = O(H) (Energy norm)
- (I) Galerkin basis are fully offline.

A data-adaptive coarse-fine scale decomposition

### Future Work

- Generalization to other non-elliptic (time-dependent) problems, e.g. the Schrödinger equation, where the non-elliptic term could be treated as a perturbation term.
- **2** Generalization to higher-order operators and higher-dimensions.

### References

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# Thanks!

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